# Speed Up Development With C2000<sup>™</sup> Real-Time MCUs Using SysConfig

TEXAS INSTRUMENTS

Nima Eskandari Applications Engineer C2000 Real-Time MCUs This white paper explains how the C2000 SysConfig graphical user interface (GUI) tool is developed to facilitate the development process for designers.

## At a glance

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#### C2000 SysConfig system initialization code generation can speed up your software development

Reliable and pre-verified code generated by the C2000 SysConfig tool is the main feature that facilitates software development for designers. Device configuration errors are caught by tool and the developer is notified of the unsupported setting.

#### Integrated PinMux tool and PinMux initialization code generation closes the gap between hardware and software designers

The C2000 SysConfig tool has built-in support for solving the device PinMux against system requirements, and provides device visualization aids.

#### Portable device initialization and code generation allows developers to create flexible and easily modifiable code

The device configuration developed in C2000 SysConfig can be easily ported between device families. Also modifications in the device configuration can be easily propagated through the rest of the already developed application code.

Designers utilizing C2000<sup>™</sup> Real-Time MCU can configure their device using C2000 SysConfig that generates reliable code and visual aids to simplify and speed up the development process. C2000 SysConfig catches incorrect device initialization settings which significantly facilitates the debugging process. Developing embedded software for initializing an MCU can be difficult for inexperience and experienced designers. New embedded devices with more advanced features and peripherals enter the market every year, making the task of configuring the device much more demanding. Small mistakes in configuring the device and its peripherals can cause the development process to slow down and frustrate the designers.

With advancements in embedded technology, both the size and capabilities of the embedded devices have grown. This makes the task of device recourse management very important. Knowing which peripherals and which device pins are used and which ones are available for further development is useful for both hardware and software designers.

Selecting the correct family of devices for a specific application can also be difficult because the requirement for the system can change. Portability of initialization settings and embedded software between device families eases the minds of developers, because they can reuse their previous investment in software development when migrating between different devices.

This white paper explores how the C2000 SysConfig tool can simplify the tasks that embedded hardware and software developers face when designing a system with C2000 real-time MCUs.

#### C2000 SysConfig system initialization code generation can speed up your software development

Developing initialization code is the first step in software development for an embedded application. This can be a tedious task and many mistakes are made due to small coding errors and not following the exact instructions given in the device's technical reference manual. Once the device is correctly initialized, the designer can continue on to develop the software for their specific application. Confidence in the correctness of the device initialization is much higher when the code developed has been previously verified by device experts. C2000 real-time MCUs can be initialized through C2000 SysConfig which generates reliable and pre-verified code for configuring your device. Device configuration errors are caught by the tool, and the developer is notified of the unsupported settings. C2000

SysConfig tool can also configure the device PinMux and visualize the device pins for each package.

C2000 SysConfig is delivered through C2000Ware (C2000 real-time MCU software development kit) and can be used with Code Composer Studio<sup>™</sup> (CCS) IDE's built-in SysConfig (System Configuration) tool or with any other supported IDE through the SysConfig tool's standalone version.



Figure 1. C2000 SysConfig in C2000Ware.

#### **Peripheral configuration**

The C2000 SysConfig allows designers to configure their peripherals through the SysConfig GUI.

Device peripherals are listed in the C2000 SysConfig tool so the designer is aware of the peripherals available in their specific device package. The configurable options for each peripheral is listed, which allows the designer to see all the different available modes. The device level inter-connects are displayed in the tool that shows the available list of signals for each MUX previously described only in the technical documentation.



Figure 2. Peripheral configuration.

More complicated peripherals such as the Configurable Logic Block (CLB), which is capable of creating custom logic inside the device, or the Dual Code Security Module (DCSM), which is used of securing the customer's intellectual property, are also included in the C2000 SysConfig ecosystem. These add-on tools will show up automatically in the tool and the designer has the options of using them in their application. The additional autogenerated artifacts from these tools will be presented to the designer seamlessly.



Figure 3. C2000 SysConfig CCS project overview.

#### **Code generation**

Automatic code generation allows developers to be confident in the correctness of their initialization code for their embedded application. As configurable options are changed, the designers can view the differences in the auto-generated code. This allows developers to understand how the embedded software changes when the requirements for the device configuration are altered.

C2000 SysConfig's auto-generated code is structured so that the designer can pick which section of the code they wish to add to their application. The designer can choose to add all of the auto-generated code or they can choose to use only the PinMux initialization feature, or they can choose to use only the initialization for a specific peripheral. This eliminates the concerns that an experienced designer would have for adopting this tool, when they already have existing and verified code. Designers who already have existing code, can compare their initialization code with the auto-generated one by C2000 SysConfig as a verification step since the autogenerated code was designed by C2000 real-time MCU experts.

Automatic Code Geneation												
CLB (1 of 8 Added)		VE ALL	board	.c								
			48	48								
MACTRO		Ш	50	50	J							
Name	myCLB0		51	51	<pre>void CLB_init(){</pre>							
CLB Instance	CL B1	•	52	52	<pre>//myCLB0 initialization</pre>							
			53	53	CLB_setOutputMask(myCLB0_BASE,							
Enable CLB			54	54	(0 << 0), true);							
Overriding Outputs	None	•	55	55	CLB_enableOutputMaskUpdates(myCLB0_BASE);							
Lock Overriding Outputs Setting			57	57	CLB_configSPIBufferLoadSignal(myCLB0_BASE_0);							
HLC Generates NMI			58	58	CLB configSPIBufferShift(myCLB0 BASE, 0);							
Theo Generates Nim			59	59	//myCLB0 CLB IN0 initialization							
Clock Prescalar CLB input r	^	60	60	CLB_configLocalInputMux(myCLB0_BASE, CLB_IN0, CLB_L								
	5		61	61	CLB_configGlobalInputMux(myCLB0_BASE, CLB_IN0, CLB_							
Data Exporting Through SPI	^	62 63	62 63	CLB_configGPInputMux(myCLB0_BASE, CLB_IN0, CLB_GP_I								
Inputs Used	Input 0. Input 1	•	64	64	CLB_selectInputFilter(myCLB0_BASE, CLB_IN0, CLB_FIL							
inputo occu	<u></u>		65	-	<pre>- CLB_disableInputPipelineMode(myCLB0_BASE, CLB_IN0);</pre>							
CLB Input 0 CLB Input Conf	iguration Input 0	$\sim$		65 +	<pre>+ CLB_enableInputPipelineMode(myCLB0_BASE, CLB_IN0);</pre>							
			67	67	//mvCLB0 CLB TN1 initialization							
Input Type Input 0	Use Global Mux	•	68	68	CLB configLocalInputMux(myCLB0 BASE, CLB IN1, CLB LC							
Global Mux Input Input 0	EPWM1A (CLB 1-4)	•	69	69	CLB_configGlobalInputMux(myCLB0_BASE, CLB_IN1, CLB_							
Enable Sync Input 0			70	70	CLB_configGPInputMux(myCLB0_BASE, CLB_IN1, CLB_GP_I							
Input Filter Input 0	— No filtering	-	71	71								
			72	72	CLB_selectInputFilter(myCLB0_BASE, CLB_IN1, CLB_FIL							
GPREG Initial Value Input 0	U	▼	73	73	CLB_d1sableInputPipelineMode(myCLB0_BASE, CLB_IN1);							
Input Pipeline Input 0			74	74 75	CLB setCDREG(muCLB0 BASE 0).							
×			76	76	CLB disableCLB(mvCLB0 BASE):							
CLB Input 1 CLB Input Conf	^	77	77	}								
		78	78									
Register Interrupt Handler			79	79								

Figure 4. Code generation and difference identification.

#### **Error detection**

Embedded devices often have many supported modes, but the device must be configured exactly as instructed by the technical documentation for each mode to operate correctly. Also, the device silicon Errata documentation notes the unsupported modes which sometimes are missed by the designers.

It is common that the development process for configuring a device is slowed down due to errors in the designer's code. These errors could be due to mistakes in programming when transferring knowledge from the technical documentation into the application software. C2000 SysConfig is capable of catching configuration errors and notifying the user of the incorrect setup.

Also, similar to error generation, warnings are generated as needed when a configuration is not necessarily wrong but requires further attention.

Invalid Signal Connection Identified

CLB (1 of 8 Added) (+) ADD	OVE ALL								
⊗ myCLB0	Ô								
Name         myCLB0           CLB Instance         CLB1	•								
Enable CLB	•								
Clock Prescalar CLB input prescalar configuration									
Enable Prescalar	•								
Prescale Value	e must er								
Data Exporting Through SPI Buffer ^									
Inputs Used Input 0, Input 1	•								
S CLB Input 0 CLB Input Configuration Input 0 ~									
Input Type Input 0 Use Global Mux	•								
Global Mux Input Input 0									
Enable Sync Input 0									
Input Filter Input 0 No filtering GPREG Initial Value Input 0 0	• •								

#### Figure 5. Error detection.

#### **Device level dependencies**

Device level dependencies can be missed by developers. Not configuring all dependencies required for a peripheral to operate correctly is a common mistake. The C2000 SysConfig tool identifies the dependencies in the device and ensures that these dependencies are configured by the designer.

C2000 real-time MCUs are highly configurable and their inter-connections, which reduces signal chain latency and eliminates requirements for external components, create dependencies between peripherals inside the device. For example, the Analog-to-Digital Converter (ADC), the enhanced Pulse Width Modulator (ePWM) and Comparator Subsystem (CMPSS) could all be interconnected to one another inside the device.

**Dependent Peripheral Identified** 

#### **Selected Peripheral** Global Parameters Settings that affect all instances Other Dependencies ASYSCTL Analog SysCtl Enable Temperature Sensor Lock Temperature Sensor Control ... Analog Reference Interna Analog Reference Voltage 2.5V DAC (1 of 2 Added) ⊕ ADD SmyDAC0 Ô Name myDAC0 DAC Instance DACA Reference Voltage ADC VREFHI reference voltage Gain Mode Gain set to 1 Load Mode Load on next SYSCLK EPWMSYNCPER Signal ePWM sync signal 1 Shadow Value 0 Enable Output Lock DAC Registers None



#### **Device level error detection**

Error detection in the designer's configuration is <u>NOT</u> limited to one peripheral at a time. Incorrect setups can be detected across dependent modules. This ensures that all dependent peripherals are configured correctly.

Unsupported Mode du Peripheral's Con	e to Dependent	
Global Parameters Settings that a	affect all instances	~
Other Dependencies		~
ASYSCTL Analog SysCtl		~
Enable Temperature Sensor		
Lock Temperature Sensor Control		
Analog Reference	Internal	*
Analog Reference Voltage	2.5V	-
AC (1 of 2 Added)	⊕ ADD 📑 REMO	OVE ALL
AC (1 of 2 Added)	⊕ ADD <b>≣</b> ≢ REMO	
AC (1 of 2 Added) OmyDAC0	(+) ADD	DVE ALL
AC (1 of 2 Added)  myDAC0 Name DAC Instance	⊕ ADD ■ REMO myDAC0 DACA	DVE ALL
AC (1 of 2 Added) ImpDAC0 Name DAC Instance Reference Voltage	⊕ ADD     ■ REMO  myDAC0 DACA ADC VREFHI reference voltage	
AC (1 of 2 Added)  Mame DAC Instance Reference Voltage Gain Mode	⊕ ADD     ■ REMO      myDAC0 DACA ADC VREFHI reference voltage Gain set to 2	
AC (1 of 2 Added)  Mame DAC Instance Reference Voltage Gain Mode	ADD      ADD	DVE ALL
AC (1 of 2 Added)  Mame DAC Instance Reference Voltage Gain Mode Load Mode	MyDACO DACA ADC VREFHI reference voltage Gain set to 2 Selected gain mode not supporte Load on next SYSCLK	OVE ALL
AC (1 of 2 Added)  Mame DAC Instance Reference Voltage Gain Mode Load Mode EPWMSYNCPER Signal	MyDACO DACA ADC VREFHI reference voltage Gain set to 2 Selected gain mode not supporte Load on next SYSCLK ePWM sync signal 1	DVE ALL
AC (1 of 2 Added)	ADD      EREMO	DVE ALL
AC (1 of 2 Added)	myDAC0 DACA ADC VREFHI reference voltage Gain set to 2 Selected gain mode not supporte Load on next SYSCLK ePWM sync signal 1 0 □	DVE ALL

Figure 7. Detecting errors in dependencies.

#### Integrated PinMux tool and PinMux initialization code generation closes the gap between hardware and software designers

Solving the device PinMux for a given application can be a difficult task. Resource management, knowing which peripherals and pins have been used and which ones are free, is extremely important in determining if the MCU is capable of all of the application's requirements. The C2000 SysConfig tool has built-in support for device PinMux, and can solve the device PinMux, and also auto-generates PinMux initialization code along with a summary CSV file. C2000 SysConfig will also visualize the device package and show the used and free package pins.



Figure 8. Device package PinMux support.

The pinmux.csv file bridges the gap between the hardware and software designer.

				The Sel	ected Pinf	Nux Option									
for the Application															
Din	Name	Colocted Model		1	2	2 4	_	c .	6	7 0	0 10 -	11	10	12 14	15
	CPIO161	Selected Mode	SPIO161	ED\A/MOA	2 *	5 • 4	0161	2 .	•	CPIO161	5 TO TO T	•	GPI0161	15 • 14	
10 09	GPI0162		SPI0162	EPW/M9B		GPI	0162			GPI0162	ESC_GPO2	9	GPI0162	ESC_F	
11 48	GPI0163		GPI0163	EPWM10A		GPI	0163			GPIO163	ESC_GPO3	n	GPI0163	ESC F	
12 B8	GPI0164		GPI0164	EPWM10B		GPI	0164			GPIO164	ESC_GPO3	1	GPIO164	ESC F	XO FRR
13 C8	GPIOO		GPIO0	EPWM1A		GPI	00		I2CA SDA	GPIO0	CM-I2CA SESC GPI0	-	GPIOO	FSITXA DO	
14 D8	GPIO1		GPIO1	EPWM1B		MFSRB GPI	01		I2CA SCL	GPIO1	CM-I2CA SESC GPI1		GPIO1	FSITXA D1	
15 A7	GPIO2	I2CB_SDA	GPIO2	EPWM2A		GPI	02	OUTPUTX	EI2CB SDA	GPIO2	ESC GPI2		GPIO2	FSITXA CLK	
16 B7	GPIO3	I2CB_SCL	GPIO3	EPWM2B	OUTPUTX	EMCLKRB GPI	03	OUTPUTX	EI2CB SCL	GPIO3	ESC_GPI3		GPIO3	FSIRXA_D0	
17 C7	GPIO4		GPIO4	<b>EPWM3A</b>		GPI	04	OUTPUTX	CANA_TX	GPIO4	MCAN_TX ESC_GPI4		GPIO4	FSIRXA_D1	
18 D7	GPIO5	MFSRA	GPIO5	EPWM3B	MFSRA	OUTPUTXEGPI	05		CANA_RX	GPIO5	MCAN_RX ESC_GPI5		GPIO5	FSIRXA_CLK	
19 A6	GPIO6		GPIO6	EPWM4A	OUTPUTX	EEXTSYNCO GPI	06	EQEP3_A	CANB_TX	GPIO6	ESC_GPI6		GPIO6	FSITXB_D0	
20 B6	GPIO7		GPIO7	EPWM4B	MCLKRA	OUTPUTXEGP	107	EQEP3_B	CANB_RX	GPIO7	ESC_GPI7		GPIO7	FSITXB_D1	
21 C6	GPIO88		GPIO88		EMIF1_A1	EMIF1_DQ GPI	088			GPIO88	EMIF1_DQM1		GPIO88	ESC_T	X0_DATA1
22 D6	GPIO89		GPIO89		EMIF1_A1	EMIF1_DQ GPI	089		SCIC_TX	GPIO89	EMIF1_CAS		GPIO89	ESC_T	X0_DATA2
23 A5	GPIO90		GPIO90		EMIF1_A1	EMIF1_DQ GPI	090		SCIC_RX	GPIO90	EMIF1_RAS		GPIO90	ESC_T	X0_DATA3
24 B5	GPIO91		GPIO91		EMIF1_A1	EMIF1_DQ GPI	091		I2CA_SDA	GPIO91	EMIF1_DQ PMBUSA_S	SSIA_TX	GPIO91	FSIRXF_D0 CLB_C	OUTP SPID_SIMC
25 C5	GPIO165	MDXA	GPIO165	EPWM11A		GPI	0165			GPIO165	MDXA		GPIO165	ESC_F	X0_DATA0
26 A4	GPIO92		GPIO92		EMIF1_A1	EMIF1_BA:GPI	092		I2CA_SCL	GPIO92	EMIF1_DQ PMBUSA_S	SSIA_RX	GPIO92	FSIRXF_D1 CLB_C	OUTP SPID_SOM
27 D5	GPIO166	MDRA	GPIO166	EPWM11B		GPI	0166			GPIO166	MDRA		GPIO166	ESC_F	X0_DATA1
28 B4	GPIO93		GPIO93		EMIF1_A2	(EMIF1_BA(GPI	093		SCID_TX	GPIO93	PMBUSA_A	SSIA_CLK	GPIO93	FSIRXF_CLICLB_C	OUTP SPID_CLK
29 C4	GPIO167	MCLKXA	GPIO167	EPWM12A		GPI	0167			GPIO167	MCLKXA		GPIO167	ESC_F	X0_DATA2
80 A3	GPIO94	)	GPIO94		EMIF1_A2	1 GPI	094		SCID_RX	GPIO94	EMIF1_BA: PMBUSA_C	SSIA_FSS	GPIO94	FSIRXG_DOCLB_C	OUTP SPID_STEn
31 D4	GPIO168	MFSXA	GPIO168	EPWM12B		GPI	0168			GPIO168	MFSXA		GPIO168	ESC_F	X0_DATA3
32 B3	GPIO95		GPIO95			EMIF2_A12GPI	095			GPIO95			GPIO95	FSIRXG_D1CLB_C	OUTPUTXBAR5
33 C3	GPIO96		GPIO96			EMIF2_DQ GPI	096	EQEP1_A		GPIO96			GPIO96	FSIRXG_CL CLB_C	OUTPUTXBAR6
34 A2	GPIO97		GPIO97			EMIF2_DQ GPI	097	EQEP1_B		GPIO97			GPIO97	FSIRXH_DOCLB_C	OUTPUTXBAR7

Figure 9. PinMux summary table.

#### Portable device initialization and code generation allows developers to create flexible and easily modifiable code

The device configuration set in C2000 SysConfig for a specific device family and package can be ported to other device families and packages. When migrating between device families, C2000 SysConfig will automatically update it's code generation templates and output the correct embedded software for the new device family. This can simplify the task of porting device initialization code for designers who are migrating between device families.

C2000 SysConfig also allows designers to name their device resources to their application specific name. This allows the initialization code and the runtime application code to be much more flixible to changes in PinMux and resource instances. For example, if the designer decides to change the GPIO number used for a task in the application, no change would be necessary to the runtime application code if the task GPIO was named through C2000 SysConfig.

In the case that some resources are not available when migrating between device families or device packages, the user is notified through warning and errors generated by the tool. If the tool is able to reassign a new resource, which can accomplish the same task, the designer is notified through a warning. If the tool is **NOT** able to reassign a new resource, the tool generates an error and forces the designer to either remove the requirement or reassign a new resource manually, which meets the same requirements.



Figure 10. Migrating between device families and device packages.

#### Conclusion

C2000 SysConfig is a powerful graphical user interface tool that configures the C2000 real-time MCUs and autogenerates embedded software, visualization diagrams, and debug artifacts that helps designers significantly with their development process. The reliable and prevalidated initialization software generated by the C2000 SysConfig tool can speed up development and help designers avoid lengthy debug sessions.

### **Additional resources**

- TI Cloud Tools
  - SysConfig
  - Resource Explorer
- C2000Ware for C2000 MCUs
  - C2000 SysConfig and examples for C2000 realtime MCUs

#### • Code Composer Studio (CCS)

- Integrated development environment (IDE) that supports TI's Microcontroller and Embedded Processors
- SysConfig tool is delivered integrated in CCS (built-in SysConfig support)
- SysConfig Standalone Version
  - SysConfig standalone version can be used alongside other IDEs which do not have the built-in SysConfig tool
- Texas Instruments: C2000 SysConfig
  - Step by step instructions for C2000 SysConfig
- C2000 SysConfig Lab 0

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